



Observational analysis of an extreme skateboarding modality: downhill skateboarding

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Abstract

Competitive downhill skateboarding is an extreme form of skateboarding that consists of going down a steeply sloping, winding road closed to traffic at maximum speed on a skateboard. The behaviours of riders in a downhill skateboarding race, where they can reach speeds of over 100 km/h, have never been studied. The objective of the work was to build an observation instrument that would allow us to record their behaviours in competition and to perform a statistical analysis of ANOVA variance and chi-square to detect the variability of this behaviour according to the positioning of the riders during the race, together with the analysis of T-Patterns. The free software LINC PLUS and Theme 6 EDU were implemented to record 23 participants in finals, semifinals and consolation finals of the Kozakov circuit (Czech Republic) between 2015-2022 in the Open category. Although no significant differences were detected in the actions based on the competitors' race positioning ($p > .05$) or in the T-Patterns, there is a significant relationship with the type of curve line ($p > .05$). In other words, the competitors followed the same line through the curve regardless of their race positioning; however, each curve was approached differently depending on its specific characteristics. The observation tool (OSKATE) can be useful in preparing for competitions in this high-speed sport, and others such as skiing and motor sports, to adapt to the conditions of different competition circuits.

Keywords: LINC PLUS, longboard, Mixed Methods, systematic observation, T-Pattern detection.

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Ana Alonso and Oriol Cardona achieve their qualification for the new Olympic sport of ski mountaineering by taking second place at the 2025 World Championships in Boi Taüll.
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Introduction

Downhill skateboarding, an extreme form of skateboarding, represents an exciting and risky sporting challenge that tests different abilities such as strength, balance and coordination as in snowboard-cross (Platzer et al., 2009; Vernillo et al., 2018), along with the ability to manage stress, maintain concentration and make quick decisions in changing conditions, as in other risky sports (Reid & Lightfoot, 2019).

Skateboarding had its origins around the 1950s in California, when creative surfers used pieces of broken surfboards, to which they added axles and skate wheels that allowed them to surf the streets when waves were scarce (Amtmann et al., 2013). Over the years, significant changes were made to the material, including changes in board shape, axle geometry, and wheel sizes, which resulted in different modes depending on the configuration of the skateboard parts (Prentiss et al., 2011), until what is now downhill skateboarding.

Downhill skateboarding is an extreme form of skateboarding, which consists of going down a road in the shortest possible time with boards made of wood, fiberglass and carbon fibre about 76 cm long and 23 cm wide, 78 mm wheels and 100-120 mm axles. Competitions, according to the organising entity, may have equipment limits: boards up to 122 cm long, axles less than 305 mm, wheels between 65-110 mm and a maximum weight of 6 kg. Competitions have timed qualifying rounds and then 4-on-4 opposition races up to the finals. Also known as downhill longboarding, the term downhill skateboarding (DHSk8) has recently become popular. After the dissolution of the International Downhill Federation (IDF) in 2023 (founded in 2012), the World Downhill Skateboarding Championship (WDSC) and the World Skate Games (WSG) are currently the international competitions.

Although there is some work on skateboarding, we found that there are few scientific studies on downhill skateboarding. We can find descriptive studies on the most common injuries (Russell et al., 2019); training and physical preparation proposals to improve the competitor's posture (tuck) (Pereira da Silva et al., 2017); research on bioenergetics, propelling oneself at different speeds (Amtmann et al., 2013; Board & Browning, 2014); and work on aerodynamics with different helmets (Hart et al., 2010).

The requirements of this sport specialty are focused on perceptual-motor decision mechanisms (balance, proprioception...) (Castañer & Camerino, 2022), and also contextual (characteristics of the environment in which it is practiced: asphalt, temperature, curve, opponents...).

Downhill skateboarding requires skills such as air braking, turning, sliding, and taking lines. In addition, the ability to perform a complete and quick stop is crucial (Kamberg, 2017). The control of these technical skills is very relevant, both to win and to simply survive and continue practicing this risky sport.

In this sport, as well as in other high-speed sports such as alpine skiing or motor sports, visuomotor conditions play an important role, as they are a tool for anticipation of the trajectory to be followed (Tuhkanen et al., 2021), and thus cause control of body direction. But in competition, when faced with an unforeseen event due to the opponents' fault, this glance and anticipation of the trajectory can no longer be easily developed. Therefore, it seems logical that during a race, riders have different behaviours depending on their visibility, the position of the rivals and their own position during the race.

Experts in high-speed sports use specific cognitive strategies and predictive brain processes to improve their performance (Lappi, 2022). Lappi (2022) explores cognitive hierarchy in high-speed sports, such as motor racing. He highlights three levels: navigation (route selection), guidance (definition of the desired route) and control (sensorimotor coordination). The main idea is that these levels process information differently, with a novelty in the interpretation of central concepts, such as landmarks and waypoints, integrated by means of chunking. Chunks can be understood as meaningful patterns stored in working memory and transferred to long-term memory. With experience, these chunks enable rapid identification of complex situations with many elements, which increases the ability to encode information despite the limitations of working memory and attention. This model can also be applied in downhill skateboarding, where prior visuomotor preparation and decision making can play a key role in the performance of the practitioners. Although chunks can help to act in complex situations, the field of view and proximity to opponents can affect this decision making.

In addition, practicing this sport involves psychological stress, an effect that varies during the race, as in other risk and opposition sports (Reid & Lightfoot, 2019). This mental stress is pervasive among athletes, along with a perception of risk and risk taking that directly influences decision making (Powell, 2007). This stress, which affects the physiology and functioning of the body, can make movements less fluid and inefficient (Reid & Lightfoot, 2019), which can lead to technical and decision errors. However, the response to certain unfavorable situations is highly individual and experience may be one of the reasons for decreased performance (Barthel et al., 2020).

In summary, downhill skateboarding is a sport in which competitors' motor patterns, visuomotor conditions, anticipatory mechanisms, decision making and emotional control can play a crucial role, since, as in motorsports (Lappi, 2022), a small mistake can make you win or lose the race.

Since the competition analysed is of high level and it is assumed that all athletes have a highly developed technique, this work focuses on analysing whether the positioning of the competitors during a downhill skateboarding race affects their actions, as well as investigating the existence of a recurrent motor pattern in this competitive modality.

Thus, the main objective was to create an instrument, using observational methodology, to identify riders' behaviours based on their race positioning and throughout the entire descent. This would allow for recording and analysing the relationship between different behaviours, including braking zone, braking type, line, stability, tuck, and interactions with rivals. The behaviours of the riders participating in the study were recorded a posteriori using this instrument for descriptive and inferential statistical analysis with analysis of ANOVA variance and chi-square, to be complemented with a T-Patterns analysis. This can provide a deeper understanding of the dynamics of competition in the sport, offering riders guidance to improve their competition strategy and preparation.

Methodology

Observational design

A P/I/M (punctual, idiographic and multidimensional) observational and intra-session design was used for the study, as there was no temporal follow-up of participants across seasons (Anguera et al., 2011). Punctual because it analysed only the semifinals and finals of the Open category of the competition at the Kozakov circuit (Czech Republic); idiographic because all participants were analysed as a unit; and multidimensional because different dimensions were analysed in relation to running position, body orientation and other biomechanical and behavioural aspects.

Participants

A total of 23 riders between 18 and 32 years of age were analysed, of which 22 were male and 1 female. They

were analysed through 20 video recordings of about 3 minutes from different competitions (finals, semi-finals and consolation finals) on the Kozakov circuit between 2015 and 2022. The category was Open, the highest one, open to everyone. The recordings chosen were public (IDF's YouTube or Facebook). Therefore, following the ethical principles guidelines described by the American Psychological Association, as they were published on the internet and recorded in a natural setting, informed consent did not have to be requested from participants (American Psychological Association, 2017). It was recorded during the months of February and March 2024.

The inclusion criteria for the videos analysed were as follows: at least one participant was followed during the entire descent, from the start of the race until they crossed the finish line; the image quality was sufficiently good; and at least two competitors participated in the recording. The exclusion criterion for the choice of recordings and competitors was the unobservability of the analysed rider's actions during the entire descent. If the competitor appeared in more than one video and met the inclusion criteria, the most recent one was selected.

Materials and instruments

The recording instrument was LINC PLUS (Soto et al., 2019, 2022) in version 1.3.2. for Mac Os Catalina 10.15.7.

Table 1 shows the observation instrument with examples of some of the criteria and categories. For the T-Patterns analysis, the criteria of stance, tuck time and body orientation on the curve were eliminated because they did not provide meaningful or consistent sequential information, as they are static or vary independently of the key behavioural sequences analysed in this study.

The study of T-Patterns in sport is conceived as a method of observational data analysis that, by means of a mathematical algorithm, makes sequentially and temporally ordered behaviours visible (Bakeman & Quera, 2011; Camerino et al., 2014). T-Patterns can also be defined as events that occur concurrently or sequentially more frequently than would be randomly expected if all events were independently distributed (Anguera et al., 2023). It is a way to discover, systematise and analyse regular structures of behaviour (Magnusson, 2020). The study of T-Patterns has been very useful in different sports and educational contexts (Castañer et al., 2020; Prieto et al., 2016).

Table 1*Observational instrument for the observational analysis of downhill skateboarding (OSKATE).*


Criteria	Categories	Code	Description
1. Stance	Goofy Regular	GOOF REGU	Front right leg Front left leg
2. Race position	1 st 2 nd 3 rd 4 th	ONE TWO THREE FOUR	Rider in first place Rider in second place Rider in third place Rider in fourth place
3. Start	Maximum Medium-low	MAX MEDL	Fast start, powerful pushes. First fast and short, then with more ADM > 9 Slow push start, with few pushes (<10), or simply letting gravity take over down the slope
4. Tuck time	Start of tuck End of tuck	STUCK ETUCK	Start of the tuck position End of the tuck position
			
5. Braking zone	Far from curve Before curve Entering curve Leaving curve Counter-curve	FAR BC EC LC COUNT	Braking is performed during a straight line or area without sharp curves and away from the curve. No main curve visible Braking is performed on a straight section or an area without sharp curves, before taking the curve line Braking is carried out in continuity with taking the curve. 1 st half of the curve, before the apex Braking is performed at the end of the curve. 2 nd half of the curve, after apex Braking is performed on the opposite side of the main curve. If the curve is toeside, a heelside slide is performed before reaching it

Table 1 (Continuation)
Observational instrument for the observational analysis of downhill skateboarding (OSKATE).







Criteria	Categories	Code	Description
6. Braking action	Carving Airbrake	CARV AIRB	Braking action due to loss of directionality. The rider steers the board sideways so as not to have such a straight trajectory Air friction braking by opening the arms like a bird and adopting a more upright posture
		CAIR	Combination of braking action due to loss of directionality and air friction
	 	FOOT	Braking by contacting with one foot on the ground
	 	GLOV	Sliding with gloved hands on the floor
	 	STAN	Sliding without putting hands on the ground
7. Orientation of the body in the curve	Toeside Heelside	TOE HEEL	The body and toes are oriented to the inner third of the curve The back and heels are oriented to the inner third of the curve

Table 1 (Continuation)*Observational instrument for the observational analysis of downhill skateboarding (OSKATE).*

Criteria	Categories	Code	Description
8. Lines	Inner third	INN	The entire line in the inner third of the curve
	Outer third	OUT	The entire line in the outer third of the curve
	Outer-Inner-Outer	OIO	Combination of outer third on curve entry, inner third at the apex, and outer third on exit
	Outer-Central-Outer	OCO	Combination of outer third at curve entry, central third at apex and inner outer on exit
	Outer-Central-Central	OCC	Combination of outer third at curve entry, central third at apex and central third on exit
	Outer-Inner-Central	OIC	Combination of outer third at curve entry, inner third at apex and central third on exit
	Inner-Central-Outer	ICO	Combination of inner third at curve entry, central third at apex and outer third on exit
	Inner-Inner-Outer	IIO	Combination of inner third at curve entry, inner third at apex and outer third on exit
	Central	CENT	The entire line in the central third of the curve
	Central-Central-Outer	CCO	Combination of central at curve entry, central at apex and outer on exit
	Central-Central-Inner	CCI	Combination of central at curve entry, central at apex and inner on exit
	Central-Inner-Central	CIC	Combination of central third on corner entry, inner third at apex and central third on exit
9. Posture and stability in curve	Tuck lean	TUCKL	Taking the curve line without breaking the tuck position
	Stable	ST	Board without sideways swings and arms tucked in the back/lower back or open without swings
	Small board oscillations	SMBO	Small rebalancing of the feet for more precise steering
	Arms oscillations	AROS	Arms rebalancing for more precise steering
	Board and arm oscillations	BAOS	Very evident foot and arm imbalances
	Speedwobble	SPEED	Temporary loss of control of the board, abrupt side-to-side oscillations of the board
10. Interaction with rivals	Stays behind	STBE	Rider slows down to avoid colliding with the opponent and stays behind him
	Slipstream	SLST	The rider takes advantage of the opponent's slipstream to get closer
	Overtaking inner third curve	OVIC	The rider overtakes the opponent on the inner third of the curve
	Overtaking outer third curve	OVOC	The rider overtakes the opponent on the outside of the curve
	Overtaking straight section	OVS	The rider overtakes the opponent in a straight section
	Contact on straight section	CONSS	The rider gently contacts the opponent on a straight section
	Contact in curve	CONCUR	The rider gently contacts the opponent in a curve, without interfering with the opponent's line
	Dodge (rider down)	DOD	The rider dodges the opponent who has fallen in the middle of the road



Procedure

The design of the observational instrument and its validation process were carried out in three successive stages: first, a review of the literature and selection of the main criteria and categories to be included in the instrument, followed by the elaboration of a proposal for an observation instrument with experts in observational methodology and in the sports specialty studied. Finally, we moved on to a content validity check of the observational instrument created through a panel of experts, to ensure that we measured what we intended to.

This third validation phase was carried out using the (Anguera & Blanco, 2003) authority criterion expressed by the judgment of a panel of 13 experts. These people had more than 4 years of experience in international competitions, some with world podiums and, among others, qualifications such as Skateboarding Level 1 Technician or graduates in Physical Activity and Sports Sciences. Through a survey developed with Google Forms, experts evaluated each of the 10 criteria of the observation instrument, assigning a validation response (YES or NO) to each of the 46 categories of the instrument. The main objective of this phase was to validate the instrument using a methodology based on the percentage of positive coincidences, considering YES-YES responses as an indicator of positive consensus on the validity of the criteria.

To analyse the data, the percentage of positive coincidences ($n = 3289$), corresponding to affirmative coincident responses among the experts, was calculated out of the total possible coincidences ($n = 3588$). This percentage was obtained by contrasting the responses of each expert ($n = 46$) with those of the other experts ($n = 12$) individually. Thus, a proportion of positive coincidences of 91.7% was obtained, which reflects a high level of agreement among the experts in the validation of the proposed criteria.

To ensure the accuracy of the results, a 95% confidence interval was calculated using the binomial model applied with the `binom.test()` function of RStudio (© 2009-2021 RStudio, PBC v.1.4.1717). The results provided a confidence interval ranging from 90.7% to 92.6%, which reaffirmed the robustness of the observed coincidence rate and, therefore, the validity of the observation instrument. After validation of the instrument and a period of training in its use, an expert in the sport and one of the authors of the study made a total of 63 records in the analysis

of two different descents. Inter-observer reliability was calculated by comparing the expert's records with those of the author through LINC PLUS and a kappa statistical index of .983 was obtained. As for intra-observer reliability, the author repeated the recording on two occasions, with a 10-day interval, and obtained a kappa index of .988. Once the reliability process was completed, data from all participants were recorded through LINC PLUS. Subsequently, the results were exported in .csv and .txt for further analysis.

Data analysis

The descriptive data, referring to the count of the qualitative variables of the study (the criteria and categories of the observation instrument [OSKATE]), are presented with frequencies and percentages (Table 2). For the quantitative variables of the study (tuck time, tuck duration, number of braking actions and records), the normality of the data distribution is checked and the trend, variation and the minimum and maximum values are presented (Table 3). For those with symmetrical distribution, the mean and standard deviation are presented; for those with asymmetrical distribution, the median and its interquartile range are presented.

To analyse the relationship between quantitative variables and final positioning, the normality assumption was tested with the Saphiro-Wilk test and its homoscedasticity with the Levene test (Table 3). To test the dependence of the variables, an analysis of ANOVA variance was performed, obtained through the nonparametric Kruskal-Wallis test, and the results were compared according to the final position of the competitor and adding the magnitude of the effect through eta squared (η^2), with $\eta^2 < .1$ trivial effect; $.1 < \eta^2 < .25$ small effect; $.25 < \eta^2 < .37$ medium effect; and $\eta^2 > .37$ major effect (Table 3).

To conduct a comparative statistical analysis of behaviour based on race positioning, the relationship between the following qualitative variables was analysed: race positioning, start, tuck time, braking zones and types, curve orientation and lines, posture and stability during the curve, curve number, and interaction with rivals. The assessment of the dependence between the different qualitative variables was performed using contingency tables with the chi-square test with Yates correction (χ^2_{cc}), estimating the intensity of association using Cramer's V (V), with $V \geq .04$ small effect, $V \geq .13$ moderate effect,

and $V \geq .22$ large effect (Table 4).

The significance level in all tests was $p < .05$ and were run with JASP computer software version 0.18.1 (Jasp Team, 2024) and Microsoft Excel version 16.66.1, both programs for MacOS Catalina 10.15.7.

Finally, to perform a T-Patterns analysis, we exported the log in .txt format to Theme6Edu software version 08 (Magnusson, 2017) with the following search criteria: a) presence of at least 3 T-Patterns; b) redundancy reduction setting of 90% for the occurrence of similar T-Patterns, c) significance level of .001, and d) Fausto option enabled to critical interval mode.

Data was published in the Research Data Repository (CORA) at the following URL: <https://doi.org/10.34810/>

[data1346](#) (Aixa-Requena, 2024).

Results

Descriptive and inferential statistics

In the results presented in Table 2, it can be seen how 100% of the riders made a maximum start; 78% of them were regulars (left leg in front). The total shares were fairly evenly distributed among those finishing in 1st, 2nd or 3rd position (~30). The majority of the braking actions were performed when taking the curve (53%) and sliding with gloves on the ground (81%). Most of the curve lines followed an

Table 2

Descriptive data of category frequencies.

Criteria	Categories	Code	Frequency	Percentage
Stance	Goofy	GOOF	5	21.74
	Regular	REGU	18	78.26
Start	Medium-low	MEDL	0	0
	Maximum	MAX	23	100
Actions by position	1 st	ONE	255	30.69
	2 nd	TWO	292	35.14
	3 rd	THREE	256	30.81
	4 th	FOUR	28	3.37
Braking zones	On straight section far from curve	FAR	10	8.62
	On straight section right before curve	RBC	9	7.76
	Entering curve	EC	62	53.45
	Leaving curve	LC	3	2.59
	Counter-curve	COUNT	32	27.59
Braking action	Carving	CARV	2	1.72
	Airbrake	AIRB	8	6.90
	Carving + Airbrake	CAIR	9	7.76
	Footbrake	FOOT	0	0
	Gloves slide	GLOV	95	81.90
	Standup slide	STAN	2	1.72
Lines	Inner third	INN	1	0.84
	Outer third	OUT	0	0
	Outer-Inner-Outer	OIO	77	64.71
	Outer-Central-Outer	OCO	7	5.88
	Outer-Central-Central	OCC	3	2.52
	Outer-Inner-Central	OIC	23	19.33
	Inner-Central-Outer	ICO	0	0
	Inner-Inner-Outer	IIO	0	0
	Central	CEN	1	0.84
	Central-Central-Outer	CCO	2	1.68
	Central-Central-Inner	CCI	0	0
	Central-Inner-Central	CIC	5	4.20

Table 2 (Continuation)
Descriptive data of category frequencies.

Criteria	Categories	Code	Frequency	Percentage
Posture and stability in curve	Tuck lean	TUCKL	2	1.71
	Stable	ST	86	73.50
	Small board oscillations	SMBO	7	5.98
	Arms oscillations	AROS	16	13.68
	Board and arm oscillations	BAOS	5	4.27
	Speedwobble	SPEED	1	0.86
Interaction with rivals	Stays behind	STBE	15	20.27
	Slipstream	SLST	22	29.73
	Overtaking inner third curve	OVIC	7	9.50
	Overtaking outer third curve	OVOC	2	2.70
	Overtaking straight section	OVSS	27	36.49
	Contact on straight section	CONSS	1	1.35
	Contact in curve	CONCUR	0	0
	Dodge (rider down)	DOD	0	0

Table 3
Descriptive and inferential data of global quantitative variables and according to final position.

Variables	Final position	n	Trend and Variation	Minimum	Maximum	CI 95%		Levene		ANOVA		
						LL	UL	F (3.19)	p	Statistic	p	η^2
Tuck time (s)	Global	23	86 (14.50) ^a	14	97							
Tuck time (s)	Global	120	12 (11.25) ^a	1	46							
Braking actions	Global	23	5.04 ± 2.46 ^b	4	9							
Registers	Global	23	37.13 ± 6.88 ^b	19	49							
Registers	1r	6	37.17 ± 4.71 ^b	31	42	33.40	40.93	2.853	.065	2.925	.403	.087
	2n	13	36.69 ± 8.35 ^b	19	49	32.15	41.23					
	3r	2	43 ± 1.41 ^b	42	44	41.04	44.96					
	4t	2	34 ± 1.41 ^b	33	35	32.04	35.96					
Tuck time	1r	6	86 (7.75) ^a	82	92	82.93	90.07	3.130	.050	1.809	.613	.108
	2n	13	78 (28) ^a	14	97	60.63	87.22					
	3r	2	82 (6) ^a	76	88	70.24	93.76					
	4t	2	90.50 (4.50) ^a	86	95	81.68	99.32					
Braking actions	1r	6	5.83 ± 1.33 ^b	4	8	4.77	6.90	2.388	.101	1.481	.687	.078
	2n	13	4.46 ± 3.05 ^b	4	9	2.81	6.12					
	3r	2	5.50 ± 0.71 ^b	5	6	4.52	6.48					
	4t	2	6 ± 1.41 ^b	5	7	4.04	7.96					

Note. ^a Median (IQR). ^b Mean ± Standard deviation. LL = Lower limit. UL = Upper limit.

ANOVA values obtained through the non-parametric Kruskal-Wallis test. $\eta^2 < .1$ trivial effect. $.1 < \eta^2 < .25$ small effect. $.25 < \eta^2 < .37$ medium effect. $\eta^2 > .37$ important effect.

Table 4*Independence between qualitative variables.*

Relationship of variable	<i>n</i>	χ^2_{cc}	Df	<i>p</i>	V
Braking zone – Braking action	116	124.380	16	< .001***	.518
Line – Stability	117	58.143	35	.008**	.315
Position during – Braking zone	116	13.571	12	.329	-
Position during – Braking action	116	8.632	12	.734	-
Position during - Lines	117	13.330	21	.897	-
Position during - Stability	117	18.921	15	.217	-
Position during - Interactions	74	79.910	15	< .001***	.600
Curve number – Braking action	116	26.854	16	.043*	.241
Curve number – Braking zone	116	71.370	16	< .001***	.392
Curve number - Lines	117	38.323	28	.092	-
Curve number - Stability	117	21.542	20	.366	-

Nota. χ^2_{cc} = chi-square with continuity correction or Yates correction.**p* < .05, ***p* < .01, ****p* < .001

V = Cramer's V: V ≥ .04 small effect, V ≥ .13 moderate effect, V ≥ .22 large effect.

outside-inside-outside pattern (64%) and were stable (73%). Regarding interactions with rivals, it is worth highlighting that 48% were overtakes, 29% were slipstreams, and 20% involved staying behind the opponent.

The descriptive data concerning the overall count of the quantitative variables under study can be found summarised in Table 3 with their trend, variation, minimum and maximum. This table shows that the trend of the total tuck time during a run was 86 seconds, with a duration of 12 seconds each time the mentioned posture was performed. Overall, riders braked a total of about 5 times (5.04 ± 2.46) per run and about 37 records (37.13 ± 6.88) were made per competitor.

The same data distributed according to final position can also be seen in Table 3, with the addition of the confidence interval (95% CI) and the data referring to the analysis of variance. In the aforementioned Table 3, it can be seen that there is no variable that has significant differences in the comparison according to the final position (*p*-ANOVA > .05), nor in the total number of records (statistic = 2.925; *p* = .403; $\eta^2 = .087$), total tuck time (statistic = 1.809; *p* = .613; $\eta^2 = .108$) or total number of braking actions (statistic = 1.481; *p* = .687; $\eta^2 = .078$), and all with a trivial (< .1) η^2 or small (.1 < η^2 < .25) effect size.

Table 4 shows the interdependence between the different qualitative variables. Of note are those where a significant dependence was detected, such as braking zone and braking action ($\chi^2_{cc}(16, N = 116) = 124.380$; *p* < .001; V = .518), curve

line and stability in the curve ($\chi^2_{cc}(35, N = 117) = 58.143$; *p* = .008; V = .315), interactions and race position ($\chi^2_{cc}(15, N = 74) = 79.910$; *p* < .001; V = .600), curve number and braking ($\chi^2_{cc}(16, N = 116) = 26.854$; *p* = .043; V = .241), and curve number and braking zone ($\chi^2_{cc}(16, N = 116) = 71.370$; *p* < .001; V = .392). All with a large effect size (V ≥ .22).

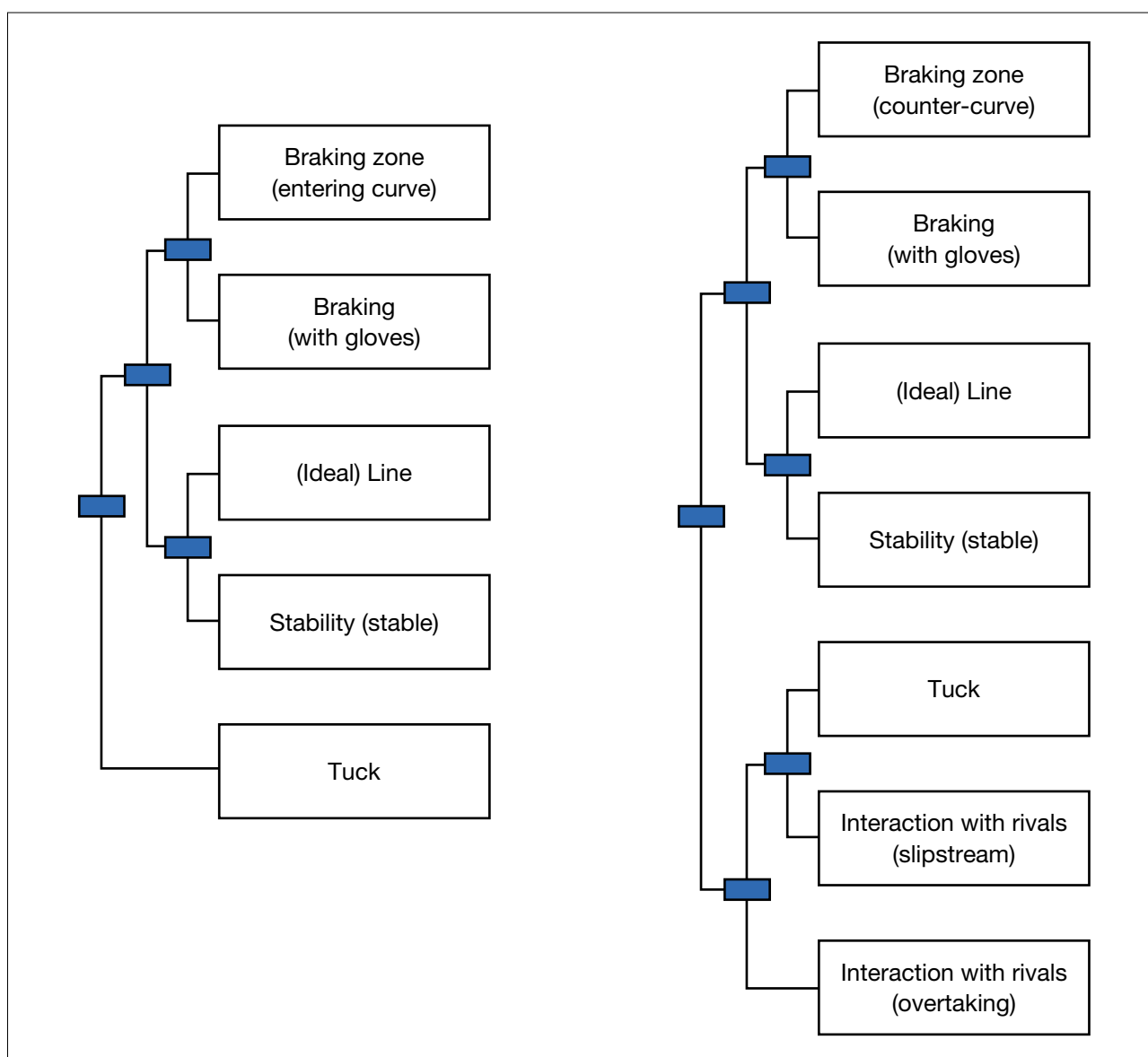
T-Pattern analysis

In the observation of the results extracted from Theme6Edu, recurrent and rapid motor patterns during a downhill skateboarding race are evidenced in two types of figures: a) T-Patterns obtained, which Figure 1 illustrates in the form of a dendrogram or tree graph, which indicate the most relevant patterns throughout the different races and participants; and b) representation of one of these patterns detected through a sequence of images of these events and their illustration (Figure 2).

The behavioural dendrogram in Figure 1 shows the two successions of typical patterns that emerged when analysing the participants' behaviours during the competition. These are patterns that follow a temporal succession over a small-time interval. The succession did not differentiate between the positioning of the participants. The mentioned patterns followed a sequence of braking zone – braking action – line – stability – tuck (+ interaction with rivals), as illustrated in Figure 2.

Figure 1

Dendrogram of T-Patterns detected in the whole sample in a downhill skateboarding race.

**Figure 2**

Example of a typical competitors' pattern.

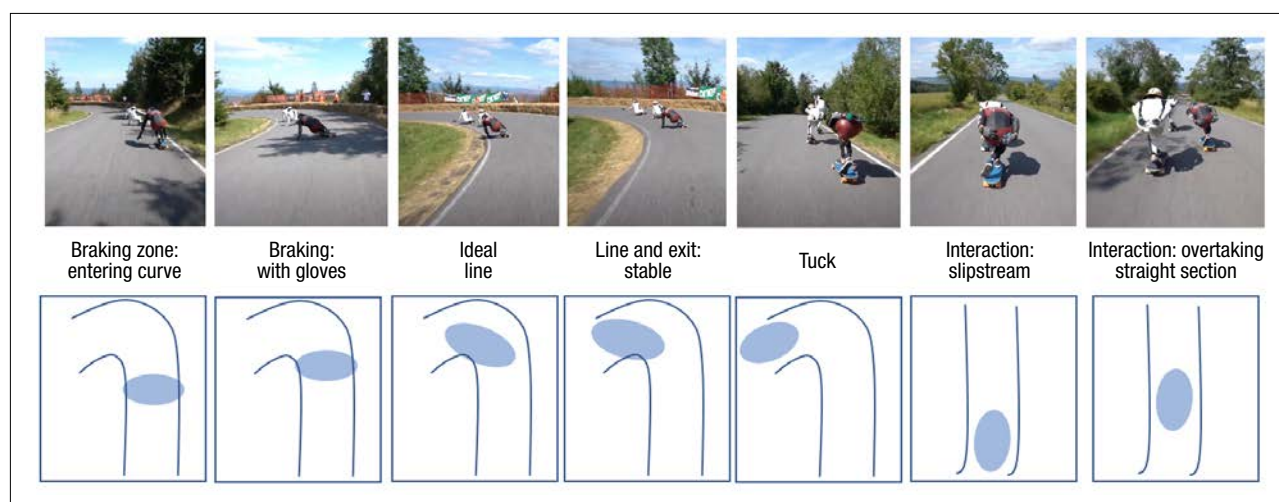
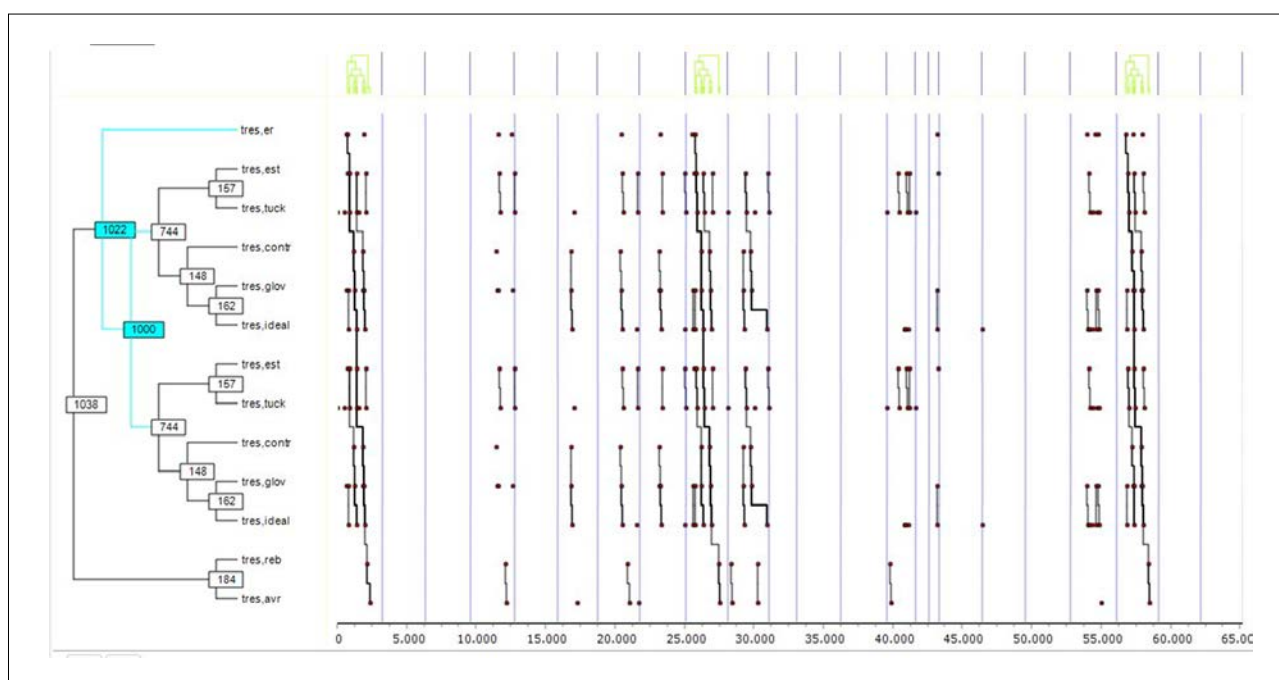


Figure 3

Example of T-Patterns dendrogram of a rider in 3rd position.



Finally, we present an example of what typically happens in the race: a linked repetition of the previously mentioned pattern (braking zone – braking action – line – stability – tuck), specifically from a rider in 3rd position (Figure 3).

Discussion

The main objective of the present study was to construct an observation instrument to analyse differences in behaviour according to the positioning of the participants during the race. The data obtained show similar results in the behaviour of competitors according to their positioning. In most cases, the participants braked while entering the curve or counter-curve, with their gloves on the ground, and followed a stable outside-inside-outside line. Therefore, no statistically significant differences have been detected in the actions of the competitors according to positioning, except for interactions, which have shown variations in type and quantity according to positioning; the first and fourth position riders are the riders with the fewest interactions. The T-Patterns also do not vary based on race positioning, and the most typical pattern follows a sequence of braking zone – braking action – line – stability – tuck (+ interaction with rivals). However, variables such as zone, braking type, stability, line and curve did have a dependency relationship between them.

These data may clash with those found in motor sports. For example, riders usually have to adjust their line according

to the conditions of the race (position, location of rivals in front or behind, road conditions...), which requires high levels of concentration in order to avoid accidents (Ledesma et al., 2015). Sometimes, this optimal line can be affected by a struggle for position and overtaking (Heilmeyer et al., 2018) or even by the psychophysiological state of the competitors (Filho et al., 2015). Therefore, the competition environment should theoretically influence participants' behaviour and their approach strategies for taking curves. However, if there is nothing to prevent them from taking the best line, riders tend to have a very stable curve line pattern, according to their style (Löckel et al., 2022).

This seems to be the case in this research, where, in general, the competitors' behaviour does not vary based on positioning, as there were not many position battles in which rivals interfered with the tracing of an optimal line. For the same reason, in the present work the T-patterns also do not vary according to positioning during the race. The differences in interactions according to position could be explained by the fact that those in first position tended not to interact with rivals and those in fourth position usually fell behind from the start and did not regain position. Therefore, most interactions were in the second and third positions.

Variables such as the braking zone, braking type, stability, line, and curve were interdependent, likely because a different line strategy was used for each curve, regardless of the competitor and their positioning.

A limitation of the study is the inability to determine

whether the recorded behaviours are a response to opponents' movements. Because of the lack of visibility of the opponents actions, especially those in front, the full understanding of the dynamics of the runners' actions is restricted. Also, the absence of telemetric data may have limited the full understanding of riders' behaviour.

Thus, the results of this study suggest that the actions in a downhill skateboarding race can vary significantly depending on the context of the competition. This has important implications for the choice of tracks to compete on and the training of competitors. This information can help competitors and coaches to choose the most appropriate training content according to the nature of the competition. For example, if a circuit has few interactions and riders' behaviour does not vary based on positioning, pre-competition training content can be more technical and focused on the ideal curve line. In this case, this will benefit competitors who are not as good at competing in shared spaces, but who excel in the qualifying rounds. Therefore, it can also help in the choice of competitions in which to participate.

Future research could explore other factors such as behavioural analysis based on the actions of rivals, along with telemetric data to get an 'x-ray' of what happens in a downhill skateboarding race.

Conclusions

On the Kozakov track, no statistically significant differences were found in running behaviour and patterns according to the positioning of the competitors. However, variables such as the braking zone, braking type, stability, line, and curve remained interdependent, likely due to the approach strategy for each curve. It is essential to explore other circuits to determine whether this phenomenon is specific to Kozakov or whether it can be generalised to other circuits with similar or different characteristics.

The observation tool (OSKATE) proposed in this paper has proven to be useful for analysing riders' behaviours in competition and can help to adapt training according to their needs. Specialists in this discipline are recommended to use the OSKATE tool.

For future research, the use of more cameras and viewing angles, as well as telemetric data, could substantially improve the understanding of competitors' behavioural patterns, although this would require significant financial investment.

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